VACUUM bIICROBALANCES AND THERMOGRAVIMETRIC APPARATUS PART I: COMMERCIALLY AVAILABLE INSTRUMENTS

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ABSTRACT

Most vacuum balances used today are electromagnetlcally compensating beam balances with sensitlvities down to the nanogram range. Deflection sensors operate elther according to the optoelectric or the electromagnetic method. One type of UHV balance is equipped with magnetic sample suspension. For special tasks, quartz spring balances and crystal oscillators are available. Beam balances in the microgram and milligram ranges are also used in thermogravimetric and sorptlon measuring apparatus. Instruments and manufacturers are compiled in tables.

HISTORICAL REMARKS

Stepwise gravlmetrlc investigation of chemlcal reactions is a very old experimental practice. The flrst thermogravlmetrlc assembly seems to have been that described by Nernst and Riesenfeld in 1903 (ref. I): a quartz balance with electric oven. In 1915 the flrst thermobalance was developed by Honda (ref. 2), who also created the name. Further developments were made in particular in France by Gulchard (ref. 3), Dubois (ref. 4), Chevenard (ref. 5) and Duval (ref. 6). The first thermogravlmetrlc apparatus was manufactured in 1945 by ADAMEL, and C. and I. Eyraud (ref. 7,8) constructed the first commercially available compensating vacuum thermobalance. In 1953 de Kaiser (ref. 9) developed the differential thermogravimetric method.

Another llne of development was started as a consequence of the application of gravimetry to sorption measurements. A prerequisite for such measurements was the development of sensltive microbalances, the first one being generally attributed to Warburg and Ihmori (ref. 10) in 1886. Petterson (ref. 11, 12) published the first gravimetric observation of adsorption in 1914.

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Further important developments were made by Rhodin (ref. 13), Gulbransen (ref. 14), McBain and Bakr (ref. 15), Gregg and Wintle (ref. 16), Cahn (ref. 17,18), and Gast (ref. 19-22). One of the most essential steps forward in this development was the introduction of vacuum, which affected the construction of balances.

CURRENT STATE OF THE ART

Today (ref. 23,24) most vacuum balances are electromagnetically compensating balances with sensitivities down to the nanogram range. Deflection sensors operate either according to a photoelectric or electromagnetic method.

Most commercial apparatus are of beam or spring types. Another type is suspension balance where the sample is freely suspended without connection to the measuring system. For special tasks, oscillation balances like crystal balances are available. These commercial balances allow investlgatlons in which vacuum and pressure, atmosphere and temperature are varied.

With respect to the first parameter, commercial vacuum microbalances are suitable for ultrahigh vacuum as well as for pressures up to 500 bar and there seems to be no other limitation to even higher pressures than the vessel of the apparatus. Fast pressure changes mostly are restricted by the nature of the sample, as powdered samples may scatter when evacuated too quickly. Also suspension parts may be affected by rapid gas streams and in such cases the use of crystal balances, vibrating bands or straln gauges may be preferable.

With respect to the atmosphere in which the balance may operate, remarkable progress has been made: many of the commercial types can be used in ultrahigh vacuum and in corrosive atmosphere. With respect to such requirements, spring, torsion and magnetic suspension balances are particularly advantageous.

Sample temperatures down to 4 K and up to 3000 K have been realised, using a liquid helium cryostat and resistance heaters with temperature transmission by radiation or by induction heating of the pan or the sample, respectively. Typical temperature increases are between zero and about 0.5 K per s; in scanning thermogravimetric experiments, temperature rises up to 10^5 K/s have been used.

Sorption and thermobalances are usually designed for maximum loads between 1 mg and 500 g. The maximum load/sensitivity ratio for beam balances amounts to 10^8 , and that for spring balances and other types which do not take advantage of mass difference measurements in the gravitational field is 10^5 .

FUTURE ASPECTS

Whereas most balances described at the VMT Conferences have been of beam or spring type, one should not underestlmate other methods for mass determination, like strain gauges, pressure sensitive semlconductors, piezoelectric crystals, vlbrating strlngs, electromagnetic and capacitive force transducer. With one exception instruments based on these princlples are not commercially designed for microbalances and, thus, not mentioned in the appended tables. They are, however, widely used for film thickness, force, pressure, or heavy load measurements. These systems in principle do not need mechanical links and thus they are not exposed to wear. The only small movements of parts having llttle mass result in a much hlgher elgenfrequency compared with the beam balance and allows the observation of fast mass changes.

In general, we must observe today a reduced activity of the manufacturers in the development of vacuum mlcrobalances. Whereas in the fiftieth and sixtieth decade such developments were the motor of progress in the balance production, in the seventleth this passed over to the area of higher load laboratory balances, industrlal and commerce scales, force and pressure transducers, which, of course, have a much bigger market. Thus, in future new vacuum microbalances may result from developments in this field.

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Table 3. Manufacturer's addresses

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